COMMON FIXED POINT THEOREMS FOR COMPATIBLE MAPPINGS

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(Received August 30, 1994 and in revised form December 6, 1994)

ABSTRACT. By using a compatibility condition due to Jungck we establish some common fixed point theorems for four mappings on complete and compact metric spaces These results also generalize a theorem of Sharma and Sahu

KEY WORDS AND PHRASES. Common fixed point, commuting mappings, weakly commuting mappings and compatible mappings

1991 AMS SUBJECT CLASSIFICATION CODE. 54H25

1. INTRODUCTION.

The following theorem was given by Sharma and Sahu [3]

THEOREM 1.1. Let (X, d) be a complete metric space and let S, T and A be three continuous mappings of X into itself satisfying the conditions

- (i) SA = AS, TA = AT,
- (ii) $S(X) \subseteq A(X)$, $T(X) \subseteq A(X)$,

and the inequality

$$egin{aligned} & [d(Sx,Ty)]^2 \leq a_1 d(Ax,Sx) d(Ay,Ty) + a_2 d(Ax,Ty) d(Ay,Sx) \ & + a_3 d(Ax,Sx) d(Ax,Ty) + a_4 d(Sx,Ay) d(Ty,Ay) \ & + a_5 [d(Ax,Ay)]^2 \end{aligned}$$

for all x, y in X, where $a_i \ge 0$ for i = 1, 2, 3, 4, 5, $a_1 + a_4 + a_5 < 1$ and $2a_1 + 3a_3 + 2a_5 < 2$, then S, T and A have a unique common fixed point in X

Unfortunately, the theorem as stated is incorrect First of all the only restriction on a_2 is that $a_2 \ge 0$ This is clearly false. In fact the inequality $a_1 + a_4 + a_5 < 1$ should have been $a_2 + a_4 + a_5 < 1$. This was only a typing error

More seriously, on examination of the proof it is seen that the inequality $2a_1 + 3a_3 + 2a_5 < 2$ was obtained by reading $[d(Ax_{2n}, Ax_{2n+2})]^2$ as $[d(Ax_{2n+1}, Ax_{2n}]^2$ This inequality should have been $a_1 + 2a_3 + a_5 < 1$ The proof continues with a 'similarity', but on following through it is seen that this time the inequality $a_1 + 2a_4 + a_5 < 1$ is required

2. PRELIMINARIES.

The following definitions were given by Sessa [2] and Jungck [1] respectively

DEFINITION 2.1. [2] Self-mappings f and g on a metric space (X, d) are said to weakly commute if and only if $d(fgx, gfx) \le d(fx, gx)$ for all x in X

DEFINITION 2.2. [1] Self-mappings f and g on a metric space (X, d) are said to be compatible if and only if whenever $\{x_n\}$ is a sequence in X such that $\lim_{n\to\infty} fx_n = \lim_{n\to\infty} gx_n = t$ for some t in X, then $\lim_{n\to\infty} d(fgx_n, gfx_n) = 0$

Note that f and g commute, then it is easily seen that they weakly commute and if f and g weakly commute, then they are compatible However, weakly commuting mappings do not necessarily commute and compatible mappings do not necessarily weakly commute For examples, see [1] and [2]

PROPOSITION 2.1. [1] Let f and g be compatible self-mappings on a metric space (X, d) with the properties

- (i) if f(t) = g(t), then fg(t) = gf(t),
- (ii) $\lim_{n\to\infty} f(x_n) = \lim_{n\to\infty} g(x_n) = t$

Then $\lim_{n\to\infty} gf(x_n) = f(t)$ if f is continuous

We now prove the following theorem

THEOREM 2.1. Let f and g be self-mappings of the set $X = \{x, x'\}$ with any metric d If the range of g contains the range of f, then the following statements are equivalent

- (i) f and g commute,
- (ii) f and g weakly commute,
- (iii) f and g are compatible

PROOF. The implication that (i) \Rightarrow (ii) \Rightarrow (iii) is clear It is therefore sufficient to show that (iii) \Rightarrow (i) The four self-mappings on X are as follows

$$Ax = x$$
, $Ax' = x'$, $Bx = Bx' = x$, $Cx = Cx' = x'$, $Dx = x'$, $Dx' = x$.

We note that A is the identity mapping on X and since we only have to prove that compatible mappings commute, we may suppose that $f \neq g$, $f \neq A$ and $g \neq A$ Further, since $f(X) \subseteq g(X)$, we only have to consider the following two cases

(a)
$$B = f$$
, $D = g$ and (b) $C = f$, $D = g$

If f and g are compatible and (a) holds, then Bx' = Dx' implies that BDx' = DBx' by Proposition 2.1 Consequently, x = x', a contradiction

Similarly, if (b) holds, then Dx = Cx implies that DCx = CDx by Proposition 2.1 and again x = x', a contradiction The conditions of the theorem can therefore hold only if either f = g or f = A or g = A and the commutativity of f and g follows This completes the proof

3. MAIN RESULTS.

Let A, B, S and T be self-mappings of a metric space (X, d) such that

$$A(X) \subseteq T(X)$$
 and $B(X) \subseteq S(X)$, (3.1)

$$\begin{split} [d(Ax, By)]^2 &\leq c_1 \max\{[d(Sx, Ax)]^2, [d(Ty, By)]^2, [d(Sx, Ty)]^2\} \\ &+ c_2 \max\{d(Sx, Ax)d(Sx, By), d(Ax, Ty)d(By, Ty)\} \\ &+ c_3 d(Sx, By)d(Ty, Ax) \end{split} \tag{3 2}$$

for all x, y in X, where $c_1, c_2, c_3 \ge 0$, $c_1 + 2c_2 < 1$ and $c_1 + c_3 < 1$

Now let x_0 be an arbitrary point in X Then since (3 1) holds, we can define a sequence

$$\{y_n\} = \{Ax_0, Bx_1, Ax_2, Bx_3, \dots, Ax_{2n}, Bx_{2n+1}, \dots\}$$
(3.3)

inductively such that $y_{2n-1} = Tx_{2n-1} = Ax_{2n-2}$, $y_{2n} = Sx_{2n} = Bx_{2n-1}$ for n = 1, 2, ...

For simplicity, let $d_n = d(y_n, y_{n+1})$ for n = 0, 1, 2, ... We need the following lemma for our main theorem

LEMMA 3.1. The sequence $\{y_n\}$ defined in (3 3) is a Cauchy sequence

PROOF. Using inequality (3 2) we have

$$\begin{aligned} d_{2n+1}^{2} &= [d(y_{2n+1}, y_{2n+2})]^{2} = [d(Ax_{2n}, Bx_{2n+1})]^{2} \\ &\leq c_{1} \max\{[d(Sx_{2n}, Ax_{2n})]^{2}, [d(Tx_{2n+1}, Bx_{2n+1})]^{2}, [d(Sx_{2n}, Tx_{2n+1})]^{2}\} \\ &+ c_{2} \max\{d(Sx_{2n}, Ax_{2n})d(Sx_{2n}, Bx_{2n+1}), d(Ax_{2n}, Tx_{2n+1})d(Bx_{2n+1}, Tx_{2n+1})\} \\ &+ c_{3}d(Sx_{2n}, Bx_{2n+1})d(Tx_{2n+1}, Ax_{2n}) \\ &\leq c_{1} \max\{d_{2n}^{2}, d_{2n+1}^{2}\} + c_{2}d_{2n}d(y_{2n}, y_{2n+2}) \\ &\leq c_{1} \max\{d_{2n}^{2}, d_{2n+1}^{2}\} + c_{2}[d_{2n}^{2} + d_{2n}d_{2n+1}] \\ &\leq c_{1} \max\{d_{2n}^{2}, d_{2n+1}^{2}\} + c_{2}\left[\frac{3}{2}d_{2n}^{2} + \frac{1}{2}d_{2n+1}^{2}\right]. \end{aligned}$$

$$(3.4)$$

If $d_{2n+1} > d_{2n}$, inequality (3 4) implies

$$d_{2n+1}^2 \leq rac{3c_2}{2-2c_1-c_2}\, d_{2n}^2 \; ,$$

a contradiction since

$$\frac{3c_2}{2-2c_1-c_2} < 1$$

Thus $d_{2n+1} \leq d_{2n}$ and inequality (3.4) implies that

$$d_{2n+1} = d(y_{2n+1}, y_{2n+2}) \leq h d(y_{2n}, y_{2n+1}) = d_{2n} \; ,$$

where

$$h^2 = rac{2c_1 + 3c_2}{2 - c_2} < 1$$
 .

Similarly,

$$d_{2n}^2 = [d(y_{2n}, y_{2n+1})]^2 = [d(Ax_{2n}, Bx_{2n-1})]^2 \le c_1 \max\{d_{2n-1}^2, d_{2n}^2\} + c_2 \left(\frac{3}{2}d_{2n-1}^2 + \frac{1}{2}d_{2n}^2\right)$$

and it follows as above that

$$d_{2n}=d(y_{2n},y_{2n+1})\leq hd(y_{2n-1},y_{2n})=d_{2n-1}$$
 .

Consequently,

$$d(y_{n+1},y_n) \le hd(y_n,y_{n-1})$$

for n = 1, 2, ... Since h < 1, this last inequality implies that $\{y_n\}$ is a Cauchy sequence in X

Now by replacing commuting mappings with compatible mappings, and by using four mappings as opposed to three, we prove the following generalization of the amended Theorem 1 1 which shows that only one of the mappings in Theorem 1 1 needs to be continuous

THEOREM 3.1. Let A, B, S and T be self-mappings on a complete metric space (X, d) satisfying conditions (3 1) and (3 2) and suppose that one of the mappings is continuous If A and B are compatible with S and T respectively, then A, B, S and T have a common fixed point z Further, z is the unique common fixed point of A and S and of B and T

PROOF. Since X is complete, it follows from Lemma 3 1 that the sequence (3 3) converges to a point z in X. The subsequences $\{Ax_{2n}\}, \{Sx_{2n}\}, \{Bx_{2n-1}\}$ and $\{Tx_{2n-1}\}$ must therefore also converge to z

Let us first of all suppose that S is continuous Since A and S are compatible, Proposition 2.1 implies that $\{S^2x_{2n}\}$ and $\{ASx_{2n}\}$ converge to Sz Using inequality (3.2) we have

$$\begin{split} [d(ASx_{2n},Bx_{2n-1})]^2 &\leq c_1 \max\{[d(S^2x_{2n},ASx_{2n})]^2,[d(Tx_{2n-1},Bx_{2n-1})]^2,[d(S^2x_{2n},Tx_{2n-1})]^2\} \\ &+ c_2 \max\{d(S^2x_{2n},ASx_{2n})d(S^2x_{2n},Bx_{2n-1}),d(ASx_{2n},Tx_{2n-1})d(Bx_{2n-1},Tx_{2n-1})\} \\ &+ c_3d(S^2x_{2n},Bx_{2n-1})d(Tx_{2n-1},ASx_{2n}) \;. \end{split}$$

Letting n tend to infinity we have

$$[d(Sz,z)]^2 \le (c_1+c_3)[d(Sz,z)]^2$$

and since $c_1 + c_3 < 1$, it follows that Sz = z

Using inequality (3 2) again we have

$$\begin{split} [d(Az,Bx_{2n-1})]^2 &\leq c_1 \max\{[d(Sz,Az)]^2, [d(Tx_{2n-1},Bx_{2n-1})]^2, [d(Sz,Tx_{2n-1})]^2\} \\ &+ c_2 \max\{d(Sz,Az)d(Sz,Bx_{2n-1}), d(Az,Tx_{2n-1})d(Bx_{2n-1},Tx_{2n-1})\} \\ &+ c_3d(Sz,Bx_{2n-1})d(Tx_{2n-1},Az) \;. \end{split}$$

Letting n tend to infinity we have

$$[d(Az, z)]^2 \le c_1 [d(Sz, Az)]^2 = c_1 [d(z, Az)]^2$$

and since c < 1, it follows that Az = z.

Now since $A(X) \subseteq T(X)$, there exists a point u in X such that z = Az = Sz = Tu. Then on applying inequality (3 2) to $[d(Az, Bu)]^2$, it follows that

$$[d(Az,Bu)]^2 = [d(z,Bu)]^2 \le c_1 [d(z,Bu)]^2 \;,$$

which implies that z = Bu. Since B and T are compatible and Tu = Bu = z, we have from Proposition (2.1) that TBu = BTu which implies that Tz = Bz. Again, on applying inequality (3.2) to $[d(Az, Bz)]^2$, it follows that

$$[d(Az,Bz)]^2 = [d(z,Bz)]^2 \le (c_1 + c_3)[d(z,Bz)]^2$$

and so z = Bz = Tz. We have therefore proved that z is a common fixed point of A, B, S and T if S is continuous.

The same result of course holds if we suppose that T is continuous instead of S.

Now suppose that A is continuous. Since A and S are compatible, it follows from Proposition (2.1) that the sequences $\{A^2x_{2n}\}$ and $\{SAx_{2n}\}$ converge to Az From inequality (3.2) we have

$$\begin{split} [d(A^2x_{2n},Bx_{2n-1})]^2 &\leq c_1 \max\{[d(SAx_{2n},A^2x_{2n})]^2, [d(Tx_{2n-1},Bx_{2n-1})]^2, [d(SAx_{2n},Tx_{2n-1})]^2\} \\ &+ c_2 \max\{d(SAx_{2n},A^2x_{2n})d(SAx_{2n},Bx_{2n-1}), d(A^2x_{2n},Tx_{2n-1})d(Bx_{2n-1},Tx_{2n-1})\} \\ &+ c_3 d(SAx_{2n},Bx_{2n-1})d(Tx_{2n-1},A^2x_{2n}) \;. \end{split}$$

Letting n tend to infinity we have

$$[d(Az,z)]^2 \leq (c_1+c_3)[d(Az,z)]^2$$

and since $c_1 + c_2 < 1$, it follows that Az = z.

Now since $A(X) \subseteq T(X)$, there exists a point v in X such that Tv = Az = z Using inequality (3 2), we have

$$\begin{split} \left[d(A^2 x_{2n}, Bv) \right]^2 &\leq c_1 \max\{ \left[d(SAx_{2n}, A^2 x_{2n}) \right]^2, \left[d(Tv, Bv) \right]^2, \left[d(SAx_{2n}, Tv) \right]^2 \} \\ &+ c_2 \max\{ d(SAx_{2n}, A^2 x_{2n}) d(SAx_{2n}, Bv), d(A^2 x_{2n}, Tv) d(Bv, Tv) \} \\ &+ c_3 d(SAx_{2n}, Bv) d(Tv, A^2 x_{2n}) \;. \end{split}$$

Letting n tend to infinity, we have

$$[d(Az,Bv)]^2 = [d(z,Bv)]^2 \leq c_1 [d(z,Bv)]^2 \; ,$$

which implies that z = Bv Since B and T are compatible and Tv = Bv = z, it follows from Proposition (2 1) that TBv = BTv which implies that Tz = Bz Similarly, applying inequality (3 2) to $[d(Ax_{2n}, Bz)]^2$, it follows that Tz = Bz = z

Since $B(X) \subseteq S(X)$, there exists point w in X such that Sw = Bz = z Using inequality (3 2), we have

$$[d(Aw,z)]^2 = [d(Aw,Bz)]^2 \le c_1[d(Sw,Aw)]^2 = c_1[d(z,Aw)]^2$$

and it follows that z = Aw Since A and S are compatible and Aw = Sw, it follows from Proposition (21) that ASw = SAw and so Az = Sz Thus z is a common fixed point of A, B, S and T if A is continuous

The same result holds if we suppose that B is continuous instead of A

Finally, let us suppose that A and S have a second common fixed z' Then from inequality (3 2) we have

$$\begin{split} [d(z',z)]^2 &= [d(Az',Bz)]^2 \leq c_1 \max\{[d(Sz',Az')]^2, [d(Tz,Bz)]^2, [d(Sz',Tz)]^2\} \\ &+ c_2 \max\{d(Sz',Az')d(Sz',Bz), d(Az',Tz)d(Bz,Tz)\} + c_3 d(Sz',Bz)d(Tz,Az') \\ &= (c_1+c_3)[d(z',z)]^2 \;, \end{split}$$

and it follows that z = z', since $c_1 + c_3 < 1$ Analogously, z is the unique common fixed point of B and T This completes the proof of the theorem.

We now prove the following common fixed point theorem for a compact metric space

THEOREM 3.2. Let (X, d) be a compact metric space and let A, B, S and T be continuous mappings of X into itself satisfying the conditions

$$A(X) \subseteq T(X) \text{ and } B(X) \subseteq S(X)$$
, (3.5)

A and B compatible with S and T respectively (3.6)

and the inequality

$$\begin{split} [d(Ax, By)]^2 &< c \max\{[d(Sx, Ax)]^2, [d(Ty, By)]^2, [d(Sx, Ty)]^2\} \\ &+ \frac{1}{2} \left(1 - c\right) \max\{d(Sx, Ax) d(Sx, By), d(Ax, Ty) d(By, Ty)\} \\ &+ (1 - c) d(Sx, By) d(Ty, Ax) \end{split}$$
(3 7)

for all x, y in X for which the right hand side of (3.7) is positive, where 0 < c < 1 Then A, B, S and T have a common fixed point z. Further, z is the unique common fixed point of A and S and of B and T

PROOF. Suppose first of all that there exists $c_1, c_2, c_3 \ge 0$, with $c_1 + 2c_2 < 1$ and $c_1 + c_3 < 1$ such that inequality (3.2) is satisfied. Then the result follows from Theorem 3.1.

Now suppose that no such c_1, c_2, c_3 exist. Then if $\{a_n\}, \{b_n\}$ and $\{c_n\}$ are monotonically increasing sequences of real numbers converging to $c, \frac{1}{2}(1-c)$ and (1-c) respectively, we can find sequences $\{x_n\}$ and $\{y_n\}$ in X such that

$$\begin{aligned} [d(Ax_n, By_n)]^2 &> a_n \max\{[d(Sx_n, Ax_n)]^2, [d(Ty_n, By_n)]^2, [d(Sx_n, Ty_n)]^2\} \\ &+ b_n \max\{d(Sx_n, Ax_n)d(Sx_n, By_n), d(Ax_n, Ty_n)d(By_n, Ty_n)\} \\ &+ c_n d(Sx_n, By_n)d(Ty_n, Ax_n) , \end{aligned}$$
(3.8)

for n = 1, 2, ... Since X is compact we may assume, by taking subsequences if necessary, that the sequences $\{x_n\}$ and $\{y_n\}$ converge to x and y respectively Letting n tend to infinity in inequality (3 8) we have, since A, B, S and T are continuous,

$$\begin{split} [d(Ax,By)]^2 &\geq c \max\{[d(Sx,Ax)]^2, [d(Ty,By)]^2, [d(Sx,Ty)]^2\} \\ &\quad + \frac{1}{2} (1-c) \max\{d(Sx,Ax) d(Sx,By), d(Ax,Ty) d(By,Ty)\} \\ &\quad + (1-c) d(Sx,By) d(Ty,Ax) \;. \end{split}$$

This is only possible if Ax = By = Sx = Ty Since A and S are compatible and Ax = Sx, it follows from Proposition (2 1) that $ASx = A^2x = SAx$

Suppose that $A^2x \neq By$ Then using inequality (3 7) we have

$$egin{aligned} &[d(A^2x,By)]^2 < c \max\{[d(SAx,A^2x)]^2,[d(Ty,By)]^2,[d(SAx,Ty)]^2\}\ &+rac{1}{2}\,(1-c)\max\{d(SAx,A^2x)d(SAx,By),d(A^2x,Ty)d(By,Ty)\}\ &+(1-c)d(SAx,By)d(Ty,A^2x)\ &=[d(A^2x,By)]^2\ , \end{aligned}$$

a contradiction and so $A^2x = By = ABy$. It follows that By = z is a fixed point of A Further, Sz = SBy = SAx = ASx = ABy = Az = z

and it follows that z is a common fixed point of S and A

Similarly, we can prove that B and T have a common fixed point v If $z \neq v$, then on using inequality (3.7) we have

$$\begin{split} [d(z,v)]^2 &= [d(Ax,Bv)]^2 \\ &< c \max\{[d(Sz,Az)]^2, [d(Tv,Bv)]^2, [d(Sz,Tv)]^2\} \\ &+ \frac{1}{2} (1-c) \max\{d(Sz,Az)d(Sz,Bv), d(Az,Tv)d(Bv,Tv)\} \\ &+ (1-c)d(Sx,Bv)d(Tv,Az) \\ &= [d(z,v)]^2 \end{split}$$

a contraction. Thus z is a common fixed point of A, B, S and T. It follows easily that z is the unique fixed point of A and S and of B and T.

Finally, note that some obvious corollaries can be obtained from Theorems 3.1 and 3.2 by letting A = B and S = T.

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